

Seat No. **MAR_APR 2025 SUMMER EXAMINATION**

101 Bachelor of Engineering
Sub. Name: Control Engineering
Sub. Code: 66241/80753/81007

Day and Date: MAY ,05-05-2025

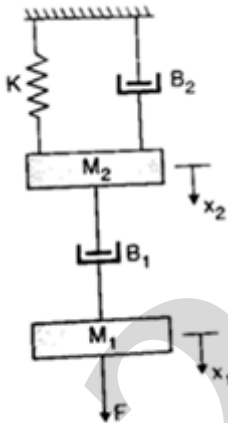
Total Marks: 70

Time: 02:30 PM To 05:00 PM

Instructions: 1. Assume suitable data wherever necessary and mention it boldly
 2. Draw neat labelled diagrams wherever necessary

Q1) Solve all from following questions**[10]**

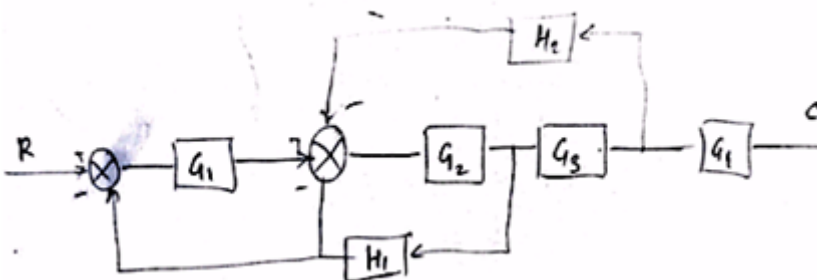
- a. For the Mechanical system as shown in the figure, draw an equivalent circuit using a force-current analogy. Also, write the system equation. **[6]**



- b. Write in details Mathematical model of Linear and Rotational system **[4]**

Q2) Question 'a' compulsory Solve any of from 'b' or 'c'**[12]**

- a. Find the transfer function of the block diagram shown in fig. by Block diagram Reduction Technique **[6]**



b.

[6]

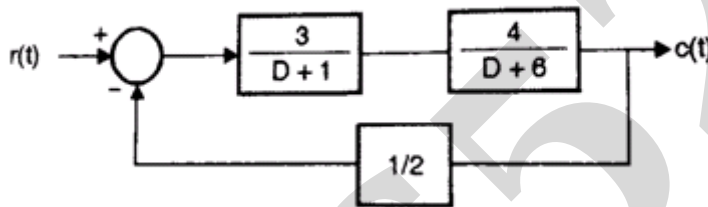
$$\frac{4fLV^2}{2gD}$$

Head loss for liquid flowing through pipe is given by $H = \frac{4fLV^2}{2gD}$ where coefficient f and acceleration due to gravity g are constants. Determine the linear approximation for the head loss. For $V_i=10$, $D_i=20$,

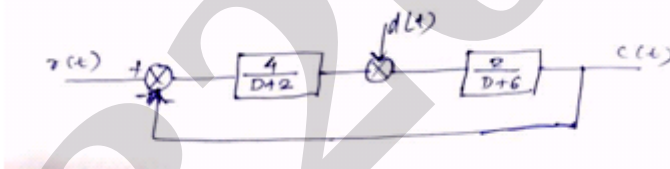
- c. Linearise the equation $V = \frac{D}{T}$, where v is velocity D is displacement & T is time. Determine the linear approximation for 'v' due to change in 'd' and change in 't' [6]

Q3) Solve any one from 'a', 'b' 'c' is compulsory from following questions [12]

- a. A system for controlling the temp. of modern office building as shown in fig. Determine the response $c(t)$ for following case - $r(t)=0$ and $C(0)=1$, $C'(0)=-2$ [6]



- b. A DC position control system is as shown in figure. Determine the response when $r(t) = 5u(t)$, $d(t)=0$ [6]



- c. If x is the input and y is the output of the system described by differential equation, $\frac{d^2y}{dt^2} + \frac{dy}{dt} + 8y = 8x$. Determine the natural frequency, damping ratio, damped natural frequency, peak overshoot and settling. [6]

Q4) Solve all questions from following [12]

- a. Sketch the root locus for the system [8]

$$G(S)H(S) = \frac{k}{s(s+1)(s+3)}$$

- b. The linear feedback system has characteristic equation as $s^3 + 2s^2 + (k+1)s + k = 0$ what is the value of k for system to be stable? [4]

Q5) Solve all questions from following [12]

- a. For unity feedback control system $G(s) = 100 / s(s+1)(s+5)$ sketch the bode plot. [8]
- b. Define phase margin? What is phase and gain cross over frequency? [4]

Q6) Solve any two from following [12]

- a. Determine state space representation and computer diagram by using series programming Method. [6]

$$y(t) = \frac{2(D+5)}{(D+2)(D+3)(D+4)} f(t)$$

- b. Determine state space representation and computer diagram of the system given by the transfer function. [6]

$$Y(S) = \frac{2S+9}{S^3+8S^2+12S+10} U(S)$$

- c. Determine state space representation and computer diagram for the system having transfer function by using series programming [6]

$$H(S) = \frac{7(S^2+3S+2)}{(S^2+8S+15)(S+7)}$$

End Of Question Paper

Important Note for Chief Exam Officer / SRPD Coordinator / Sr Supervisor/ Student -

This Question Paper may be distributed for following Subjects as common code.

सदरची प्रश्नपत्रिका खालील विषयांकरिता वितरित करता येईल.

- 1] (101) Bachelor of Engineering (81007) Control Engineering Part 3 SEM 5
- 2] (101) Bachelor of Engineering (66241) Control Engineering Part 3 SEM 5
- 3] (1154) B.Tech. CBCS (80753) Control Engineering Part 3 SEM 5